

CMPSCI 691AD - General Purpose Computation on the GPU

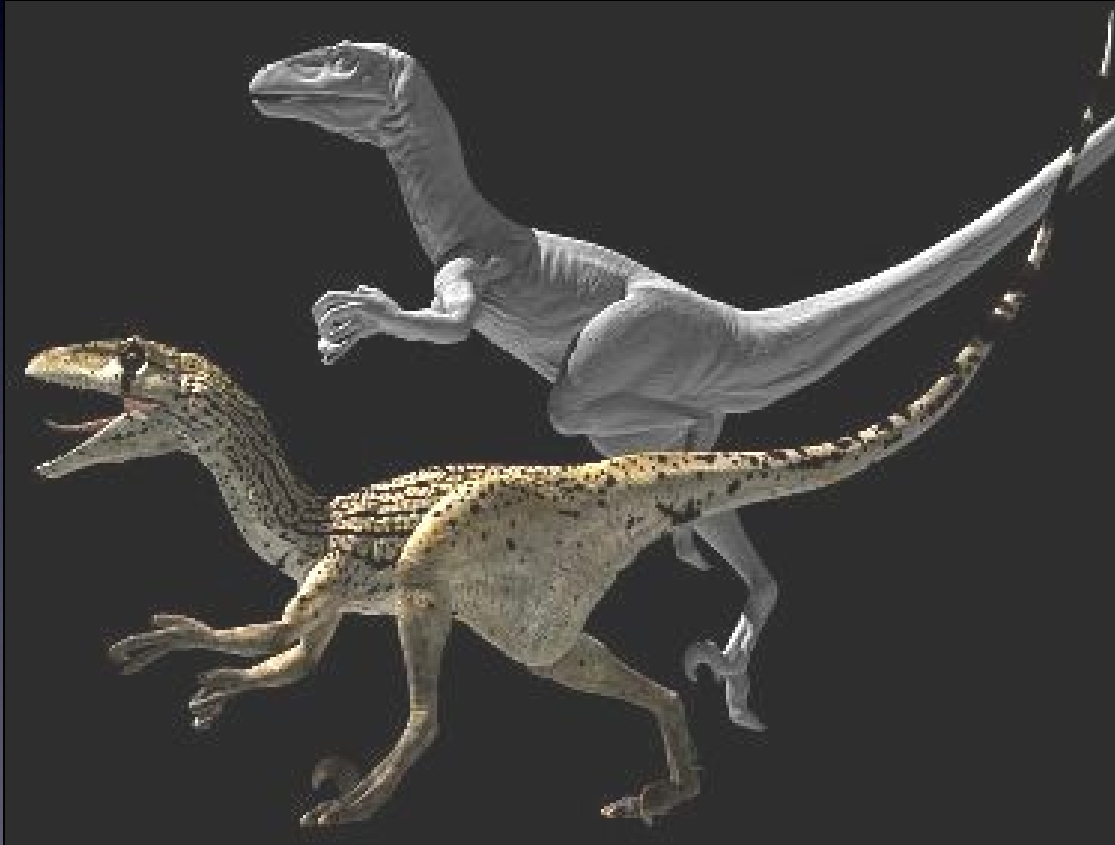
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Lecture 13: Texture Filtering

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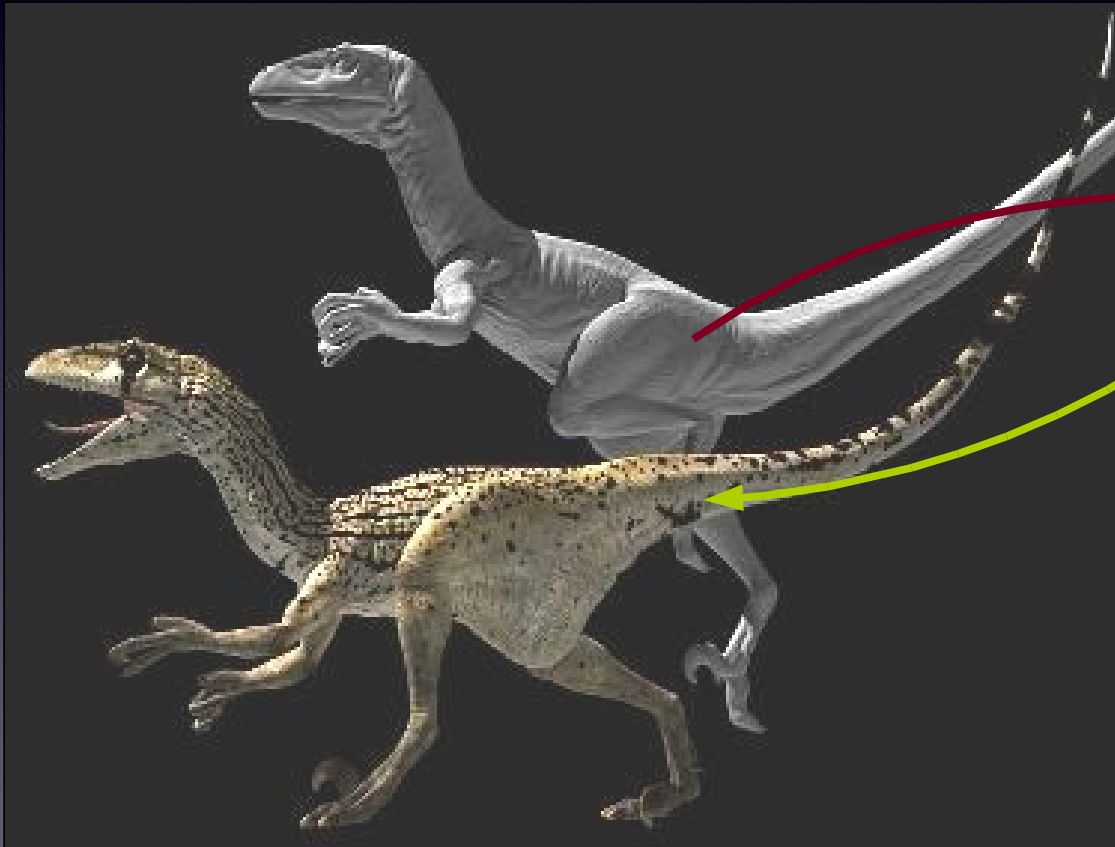
Textures

- Textures provide an efficient way to add surface details without increasing geometric complexity.



Parametrization, UV Mapping

- Determining how each point on the 3D model is mapped to a 2D texture: texture coordinates.



Parametrization, UV Mapping

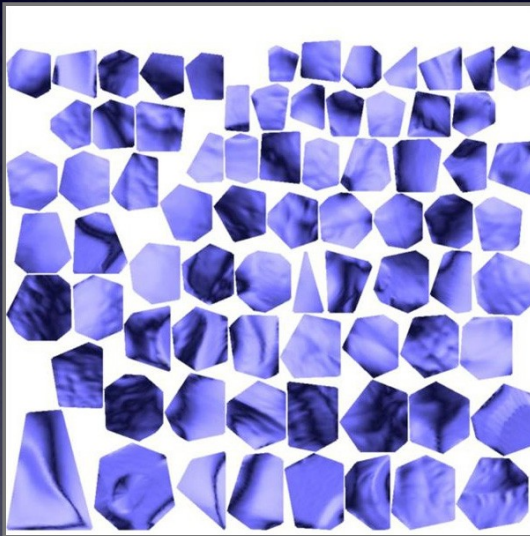
- Determining how each point on the 3D model is mapped to a 2D texture: texture coordinates.
- In general a difficult problem:
 - Maintaining 3D coherence and continuity
 - Distortion

Parametrization, UV Mapping

- Determining how each point on the 3D model is mapped to a 2D texture.



Charts



Atlas

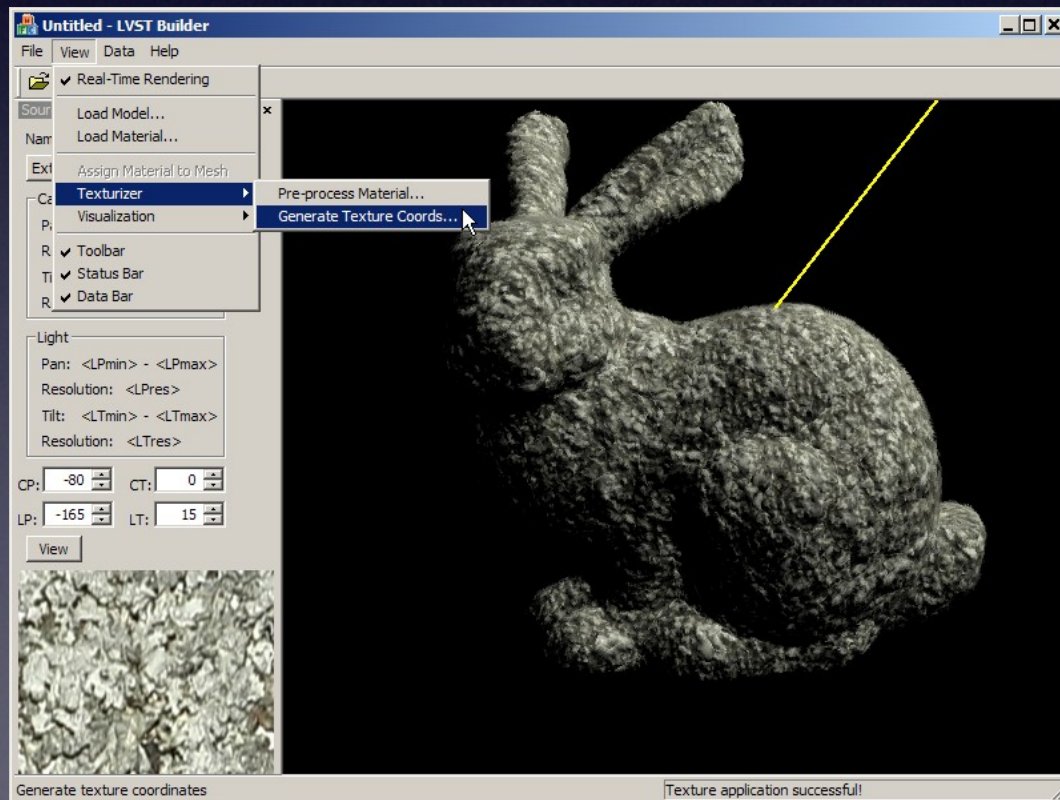


Surface

[Sander 2001]

3D Textures

- Volumetric textures
- Can use 3D point to directly index into the texture, no parametrization needed.

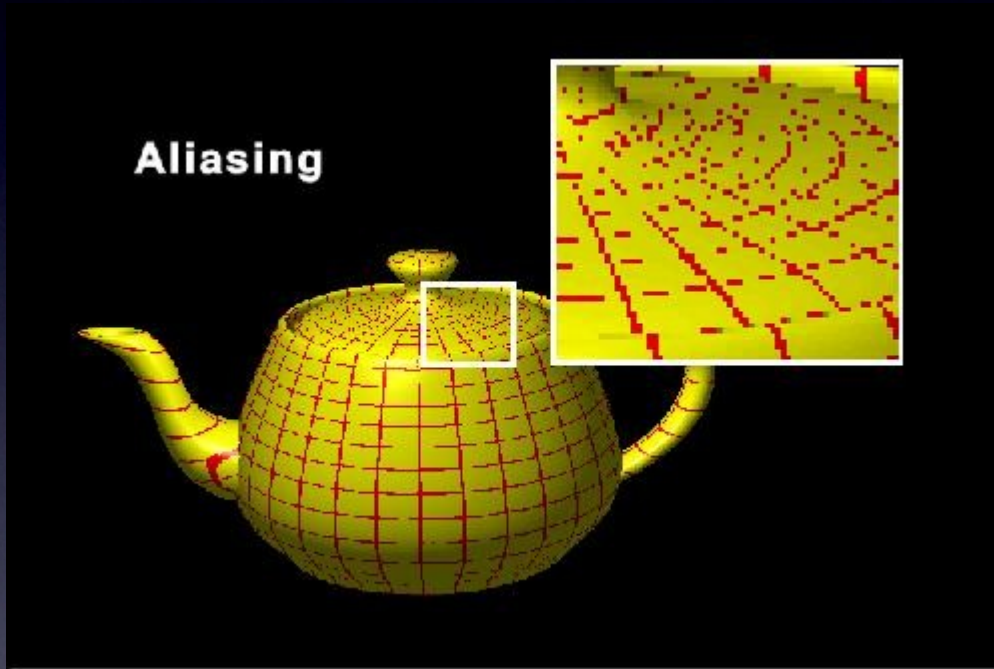


Texture Mapping

- How to apply texture mapping?
 - 1. Rendering to generate pixels
 - 2. At each pixel, figure out the texture coordinate
 - 3. **Index into the texture map** (using the texture coords) to obtain a texel value
 - 4. Apply the texel value to generate color for pixel.

Texture Map Aliasing

- Nearest sampling is very bad: aliasing.



Texture Map Aliasing

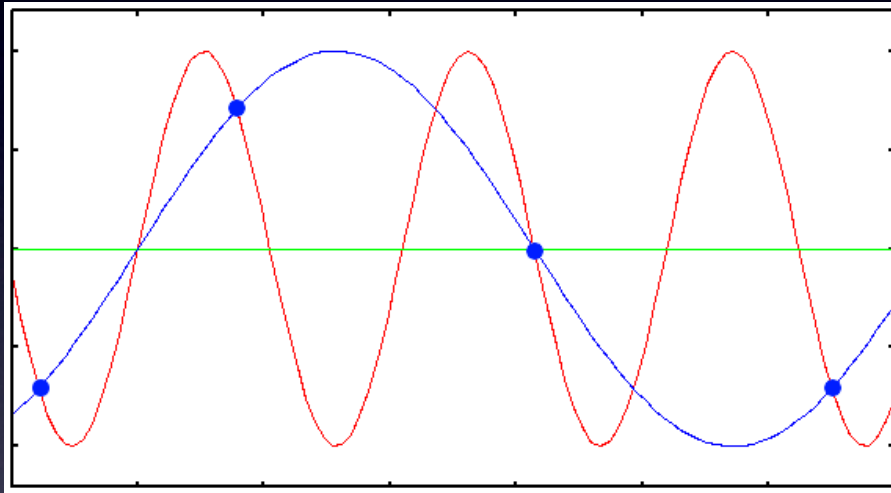
- Nearest sampling is very bad.
- (Bi)-linear interpolation improves, but still insufficient to completely eliminate aliasing. Why?

Texture Map Aliasing

- Nearest sampling is very bad.
- (Bi)-linear interpolation improves, but still insufficient.
- Fundamental problem: image resolution and texture resolution are **not the same**.
 - Image res = Texture res: OK
 - Image res > Texture res: bilinear interpolation
 - Image res < Texture res: aliasing! need average/filter.
- Think about perspective projection.

Texture Map Aliasing

- Theory in digital signal sampling to explain aliasing.



- Sampling rate must be sufficient (twice the bandwidth of the source signal) to reproduce the original signal.

Texture Map Aliasing

- Example of perspective projection:



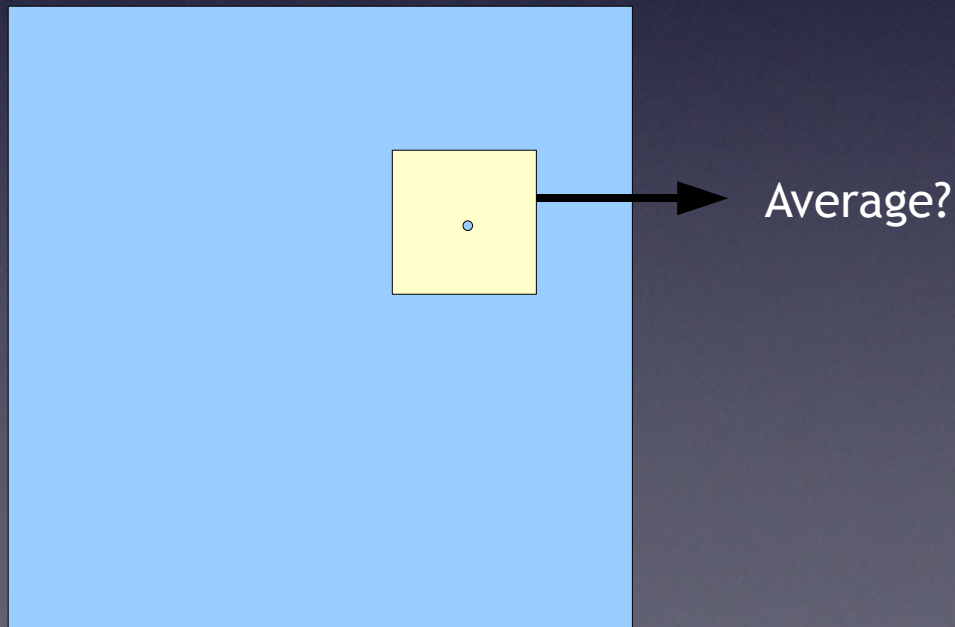
Texture Map Aliasing

- What if sampling rate is limited anyways?
- Solution: filter (smooth) the input signal.



Texture Filtering

- Basically, we want to very efficiently compute the average of a neighborhood of texels.
 - The size of the neighborhood maybe arbitrary and spatially varying.
 - Must be efficient to compute and store.



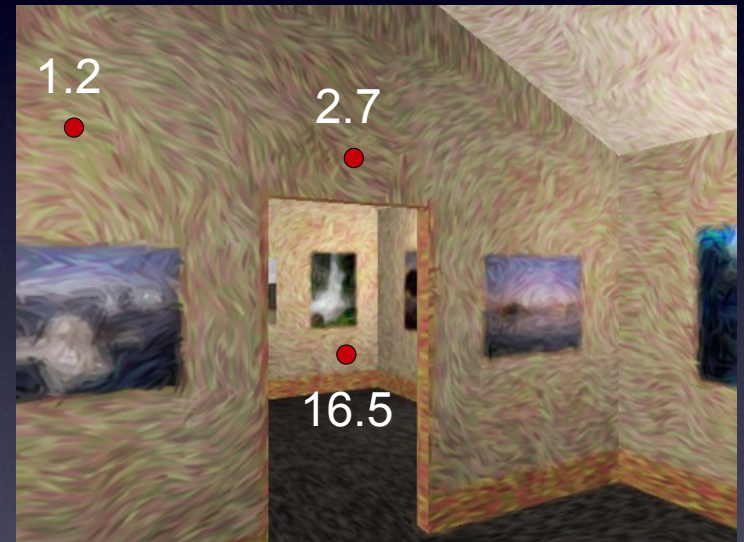
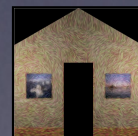
Mip Maps

- Keep textures prefiltered: a hierarchy of textures, each layer is a 2x2 reduction from the previous layer.
- Mip: comes from latin, meaning “much in a small space”



Mip Maps

- Interpolate between two mipmap levels to approximate arbitrary neighborhood size: trilinear interpolation.



Mip Maps

- No filter vs. Mip Map Filtering



AAAAAAGH
MY EYES ARE BURNING



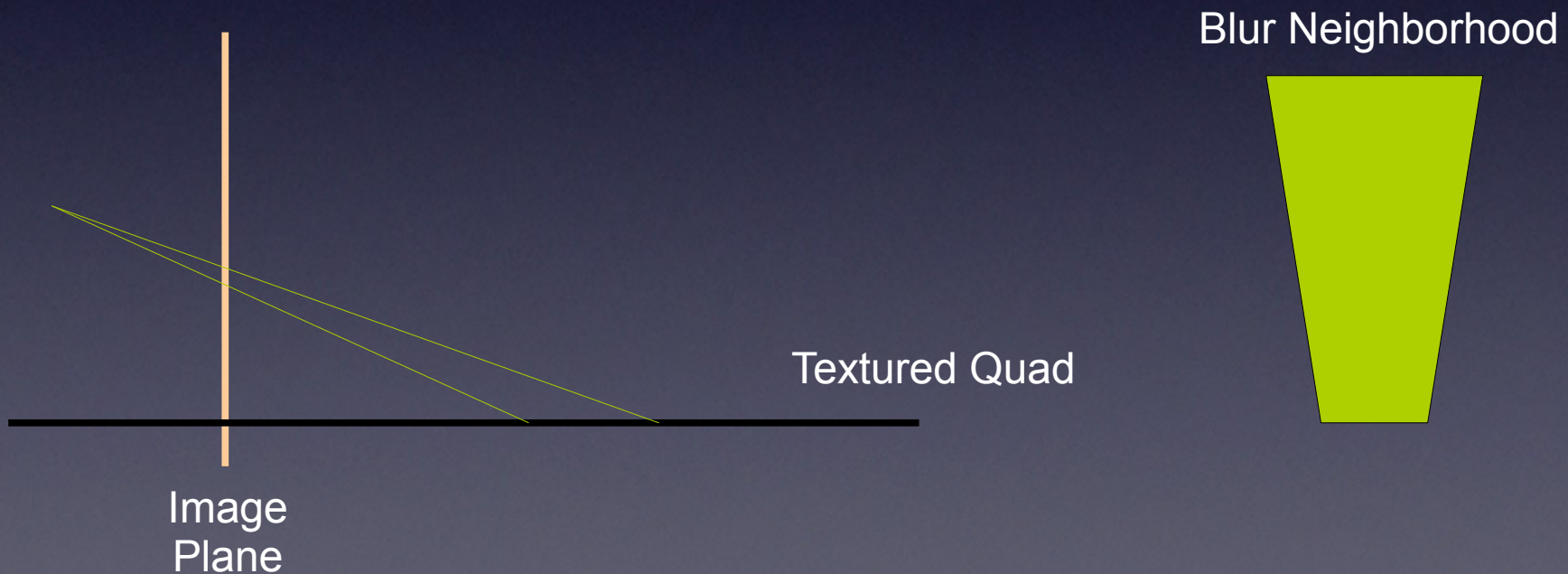
Where are my glasses?

Mip Maps

- How to build Mip Maps?
 - 2D reduction
 - Hardware accelerated in OpenGL
- Advantages
 - Fast, efficient

Mip Maps

- Disadvantages
 - Isotropic filtering, resulting in over-blurring
 - Can be solved by anisotropic mipmapping

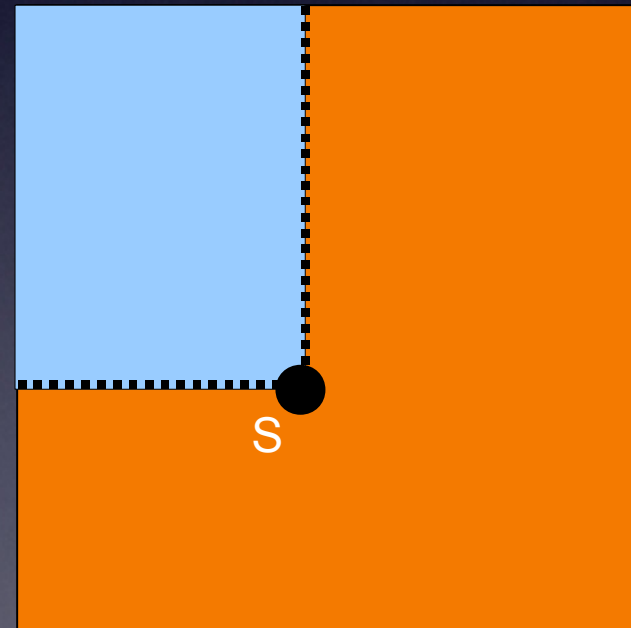
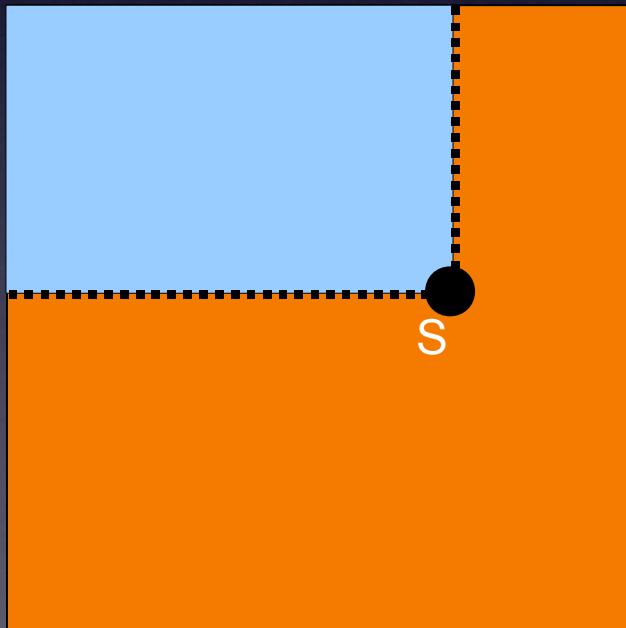


Summed-Area Table (SAT)

- SAT is a way to quickly computing the sum of a rectangular subset of a 2D array.
 - Idea can similarly apply in 1D or 3D. 1D as example.

Summed-Area Table (SAT)

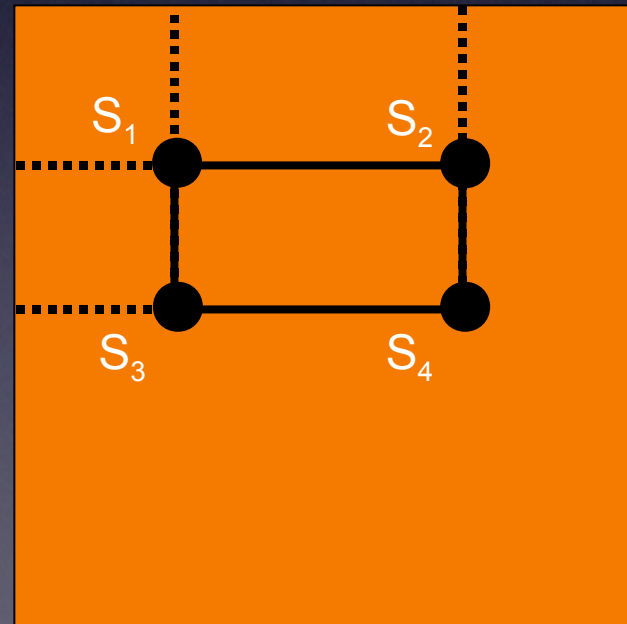
- Pre-compute partial sums
 - Similar to pre-fix sum, but in 2D
- Compute the sum of an arbitrary rectangular subset?



Summed-Area Table (SAT)

- Pre-compute partial sums
 - Similar to pre-fix sum, but in 2D
- Compute the sum of an arbitrary rectangular subset?
 - 2 subtracts, 1 add

$$S = S_4 - S_2 - S_3 + S_1$$



Summed-Area Table (SAT)

- SAT can quickly integrate texels covered by a rectangular sub-area: more anisotropic capability.

- Mip Map Filtering vs. SAT Filtering



Summed-Area Table (SAT)

- How to build an SAT?
- Advantages and Disadvantages.

Summed-Area Table (SAT)

- How to build an SAT?
 - Can apply +Scan on rows and subsequently on columns
 - If the texture is big enough, can process entire rows (then columns) in parallel using sequential scan.
- Advantages
 - Fast, more anisotropic
- Disadvantages
 - High precision (more bits) needed
 - What about non-axis-aligned rectangle, or neighborhood with more weird shapes?

OpenGL Interoperability

- OpenGL Buffer Objects can be mapped to CUDA address space.

1. In the **very beginning**, need to initialize:

```
cudaGLSetGLDevice();
```

2. Register a buffer object with CUDA

```
cudaGLRegisterBufferObject(GLuint buffer);
```

3. Map the buffer object to CUDA memory space

```
cudaGLMapBufferObject(void **devPtr, GLuint  
buffer);
```

4. Launch CUDA kernel to process the buffer

5. Unmap and unregister

OpenGL Interoperability

- To handle textures, currently need to use `glTexImageSub2D` and `glReadPixels` to transfer data between pixel buffer objects (PBOs) and textures.
 - PBOs can be mapped to CUDA space as before.